

Mars Exploration Rover

MER Landing Site Hectometer Slopes

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- Assume all topography on Mars is self-affine: implies that a fractal scaling law can be applied to the rms height deviation, ζ :

$$\zeta = \langle [z(x) - z(x+L)]^2 \rangle^{1/2}$$

where L is a lag interval along a profile; $\zeta = \zeta(L)$.

- The scaling behavior is:

$$\zeta(L) = \zeta(L_0) [L / L_0]^H$$

- A log-log plot of ζ vs. L will be linear under the self-affine assumption with Hurst exponent, H, as slope of line.
- The rms slope for lag L is

$$s_{rms} = \text{atan} (\zeta(L) / L)$$

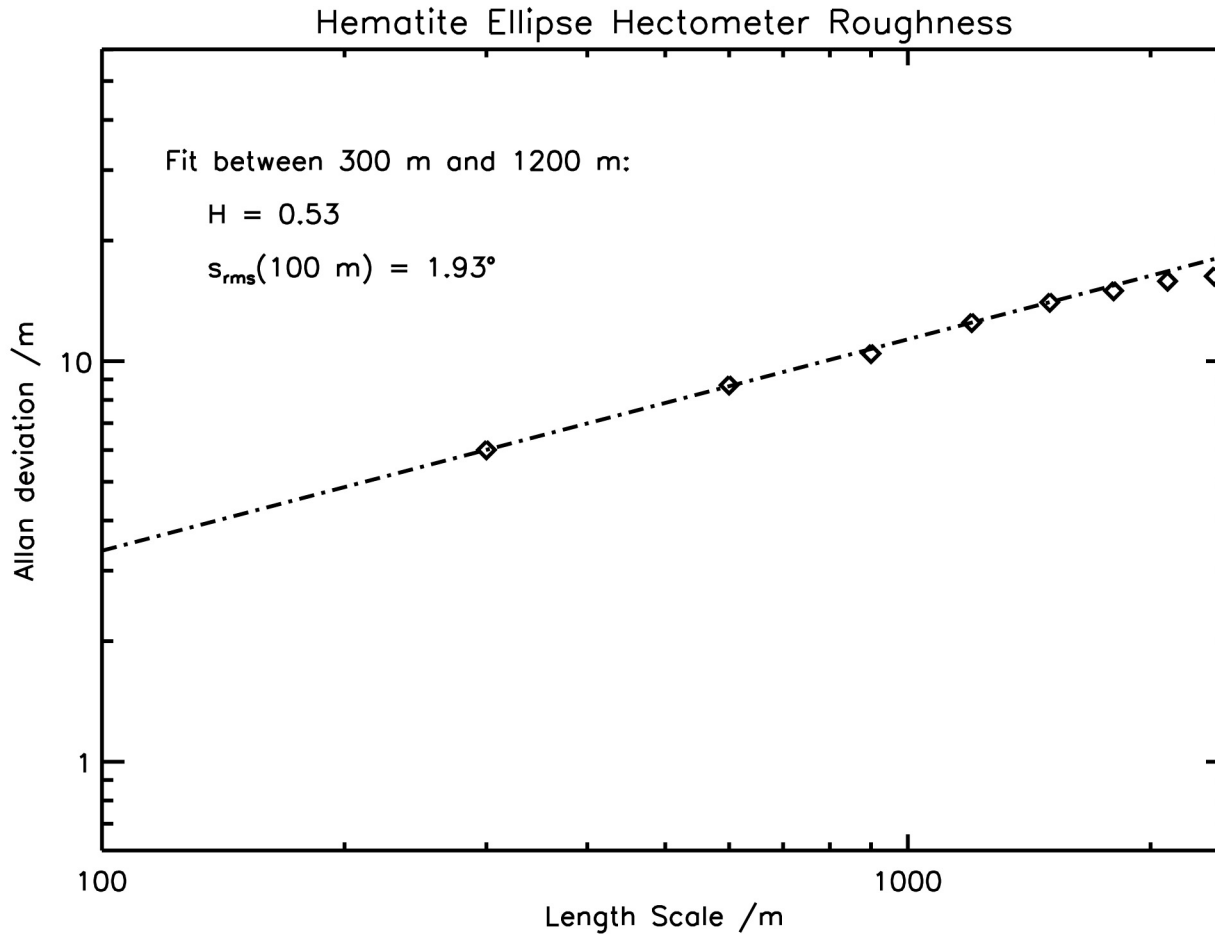
- Use MOLA profiles to calculate $\zeta(L)$ for L = 300 m to 3000 m. Fit the linear region in the range L = 0.3 km to 1.2 km and extrapolate back to $\zeta(100 \text{ m})$ to get $s_{rms}(100 \text{ m})$



Example Allen Deviation Fit



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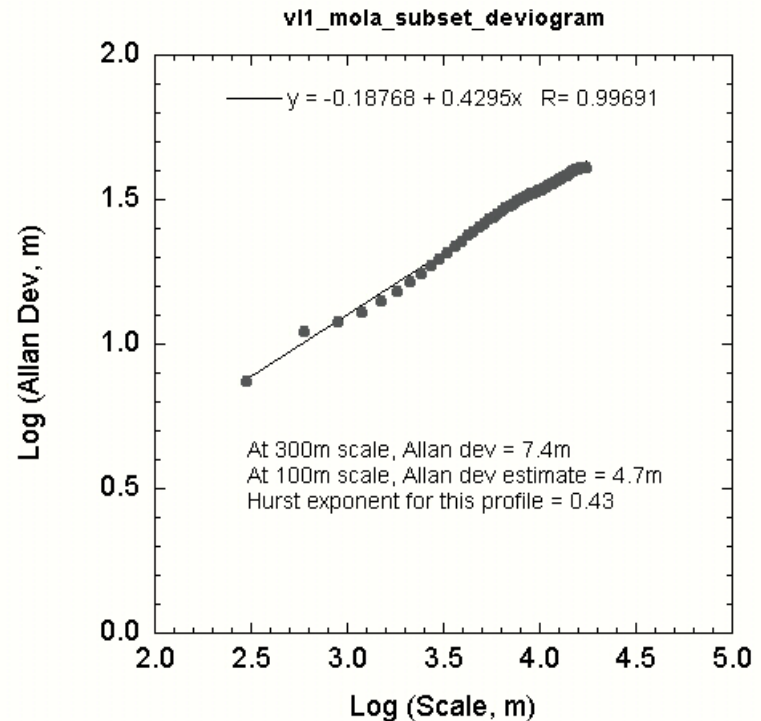
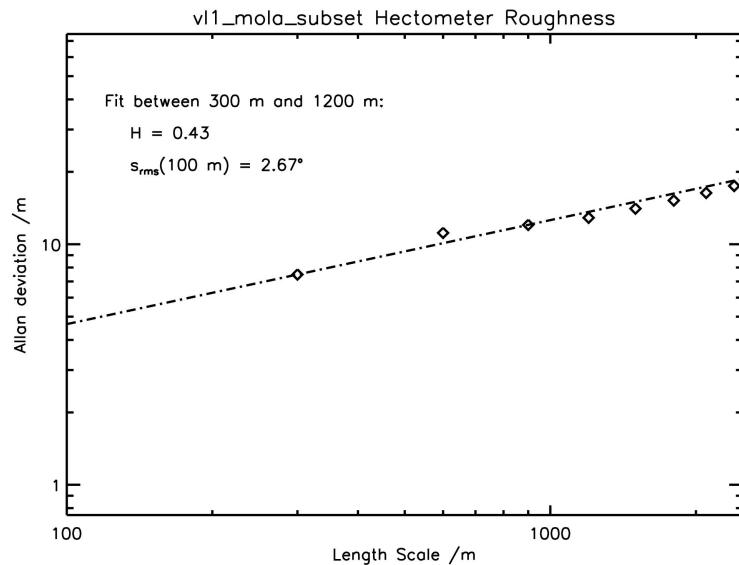
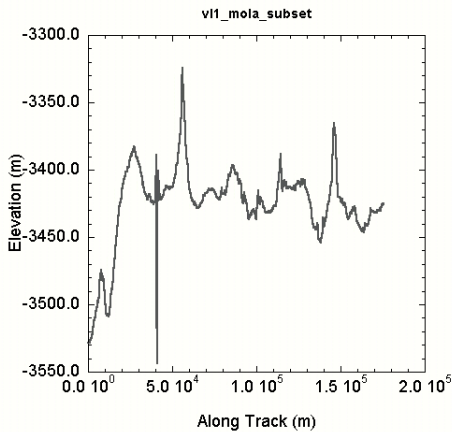


Method Check



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- MOLA track no. 1601 from 20.9599°N to 23.9841°N.
- Comparison of Shepard and Haldemann processing.
- Allan deviations for each lag are identical; both codes are doing the same things.
- Agreement of fits in this case are fortuitous as Haldemann fits 300 m to 1200 m only, which Shepard fits all profile scales.





MER Landing Sites



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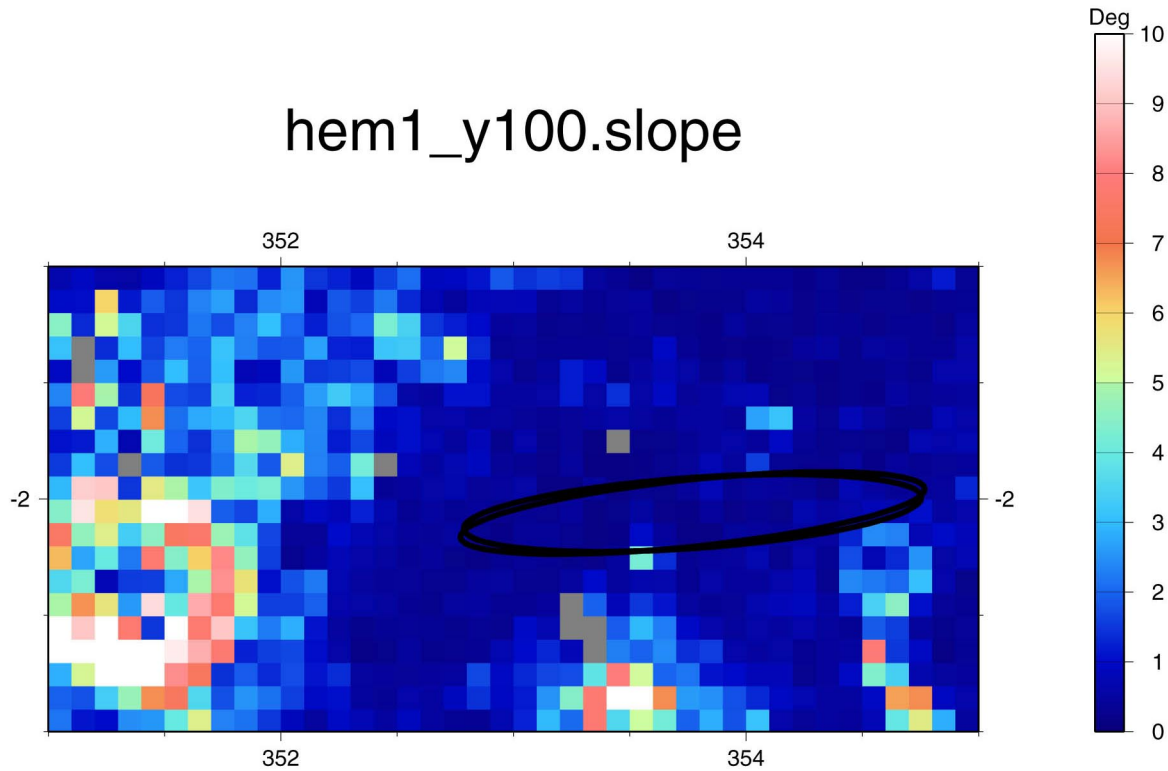
Site	H	$\zeta(100\text{ m})$ /m	$S_{\text{rms}}(100\text{ m})$ /deg.	$\zeta(1\text{ m})$ /m	$S_{\text{rms}}(1\text{ m})$ /deg.
Hematite	0.53	3.4	1.9	0.30	16.7
Melas	0.81	9.9	5.7	0.24	13.5
Gusev	0.56	5.8	3.3	0.44	23.8
Isidis	0.51	2.6	1.5	0.25	14.0
Athabasca	0.76	4.3	2.5	0.13	7.4
Eos	n/a	n/a	n/a	n/a	n/a
MPF (326.4°E,19.3°N \pm 0.2°)	0.37	5.0	2.9	0.92	42.6
MPF (0.5° “radius”)	0.77	5.0	2.9	0.15	8.5
VL1 (311.8°E,22.3°N \pm 0.2°)	0.53	1.8	1.0	0.15	8.5



Site Hectometer Slope Map: Hematite



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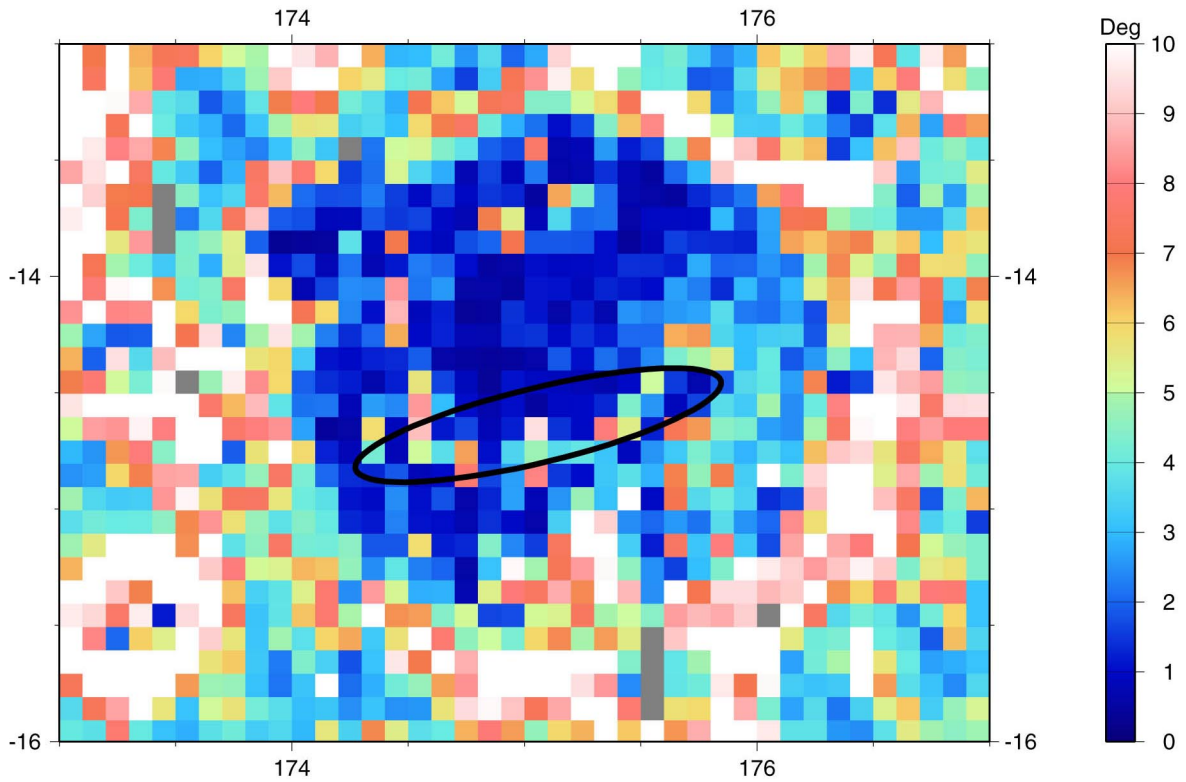


Site Hectometer Slope Map: Gusev



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gus_y100.slope



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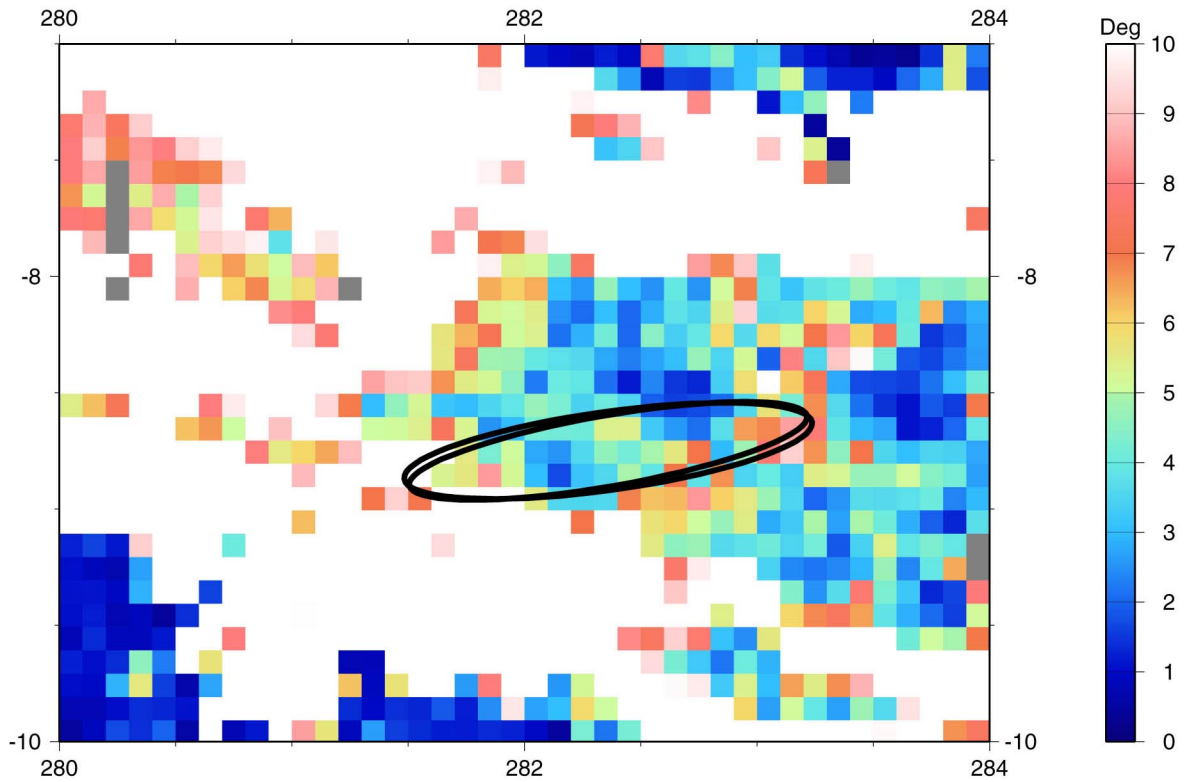


Site Hectometer Slope Map: Melas



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mei_y100.slope



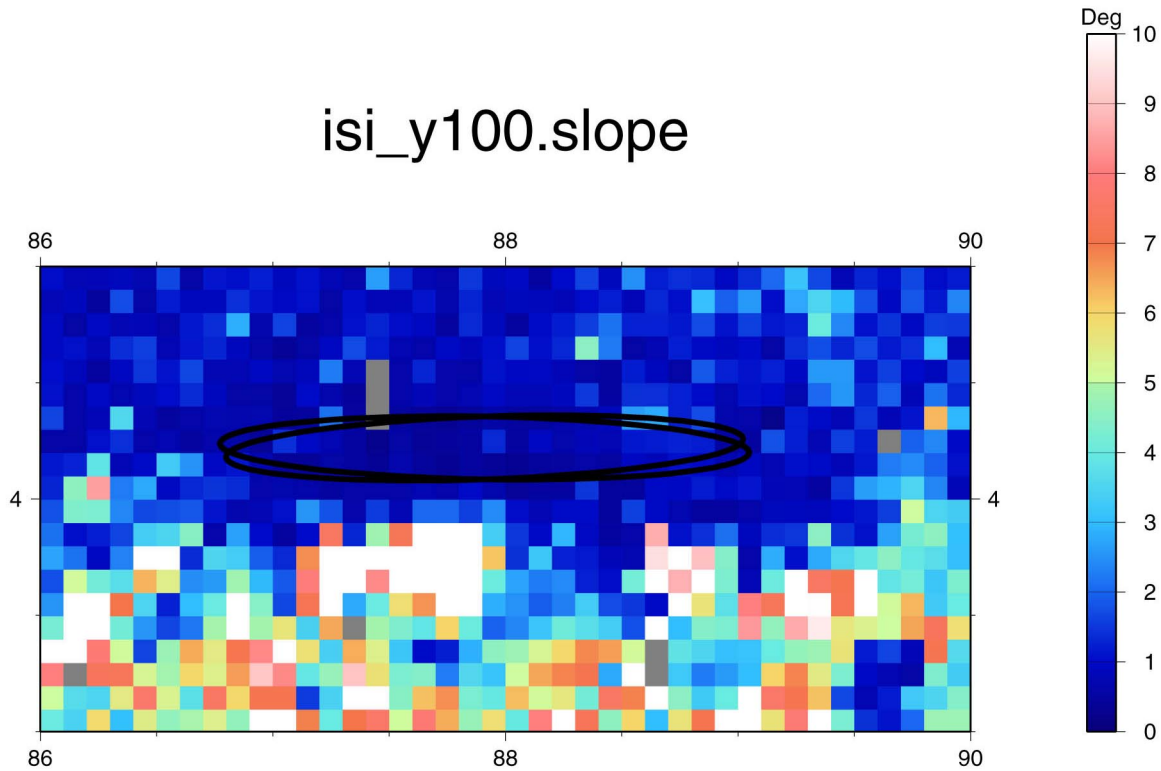
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Site Hectometer Slope Map: Isidis



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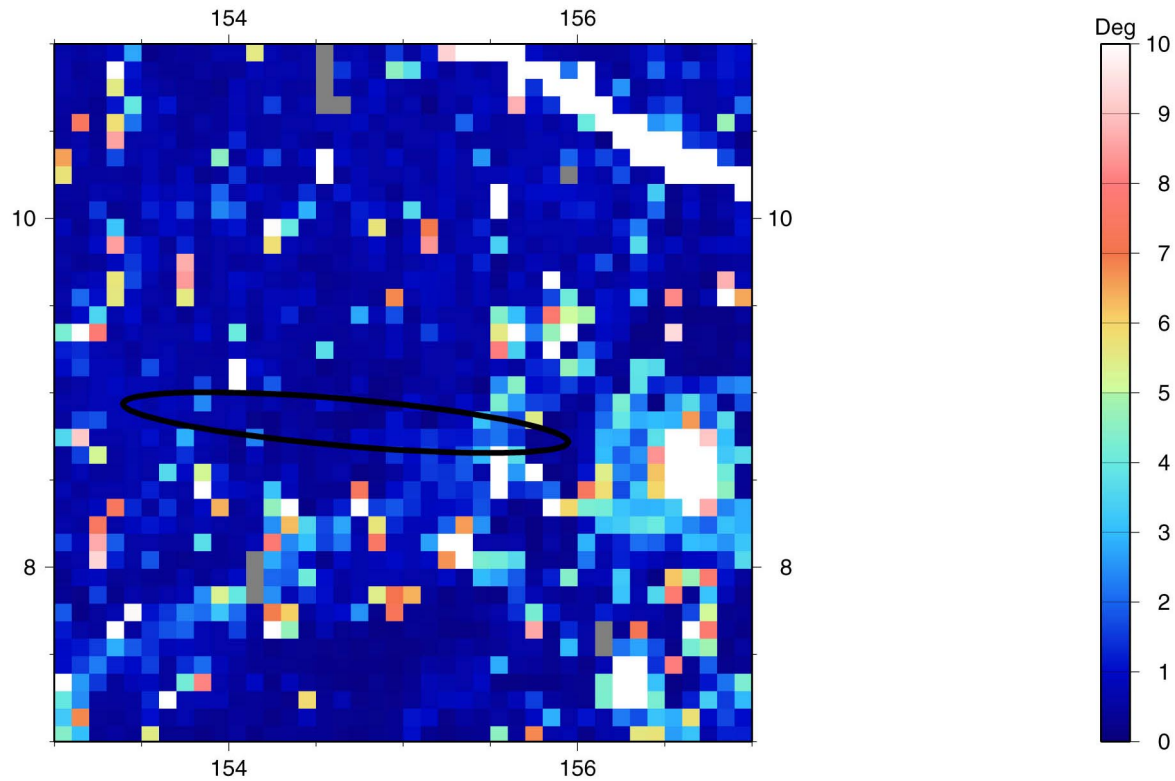


Site Hectometer Slope Map: Athabasca

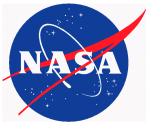


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ath_y100.slope



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Site Hectometer Slope Map: Eos



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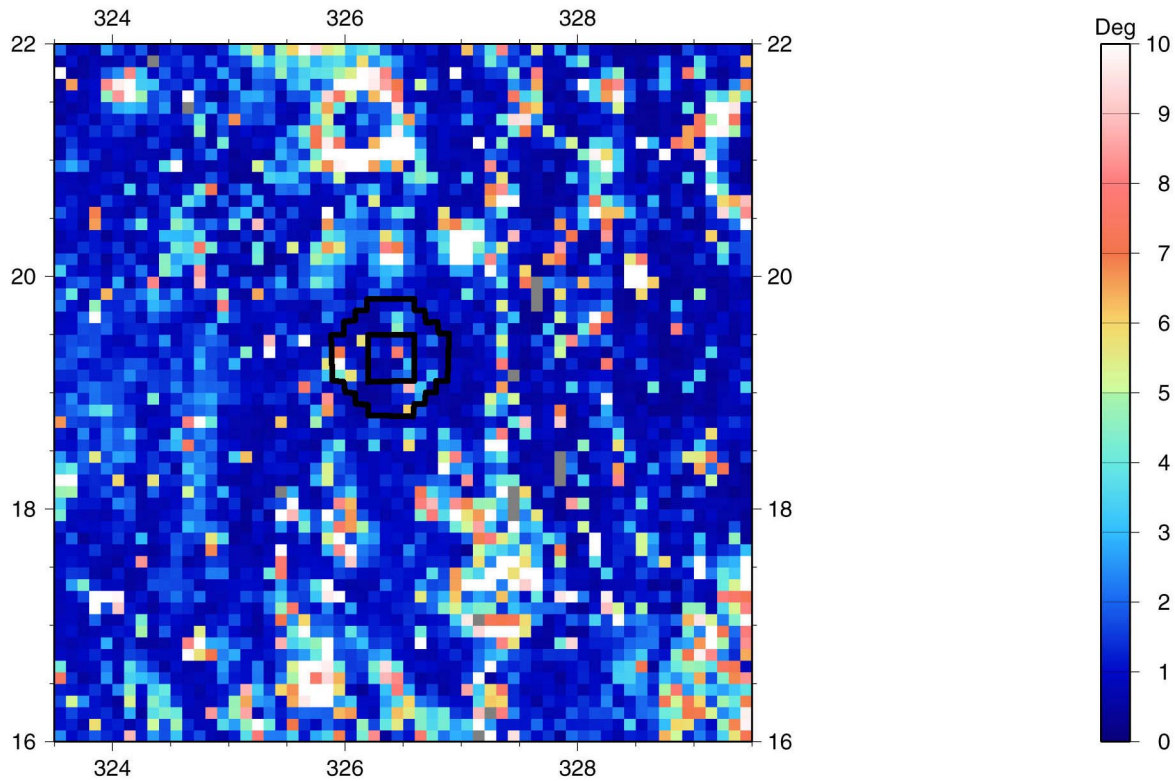


Site Hectometer Slope Map: Pathfinder



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mpt_y100.slope



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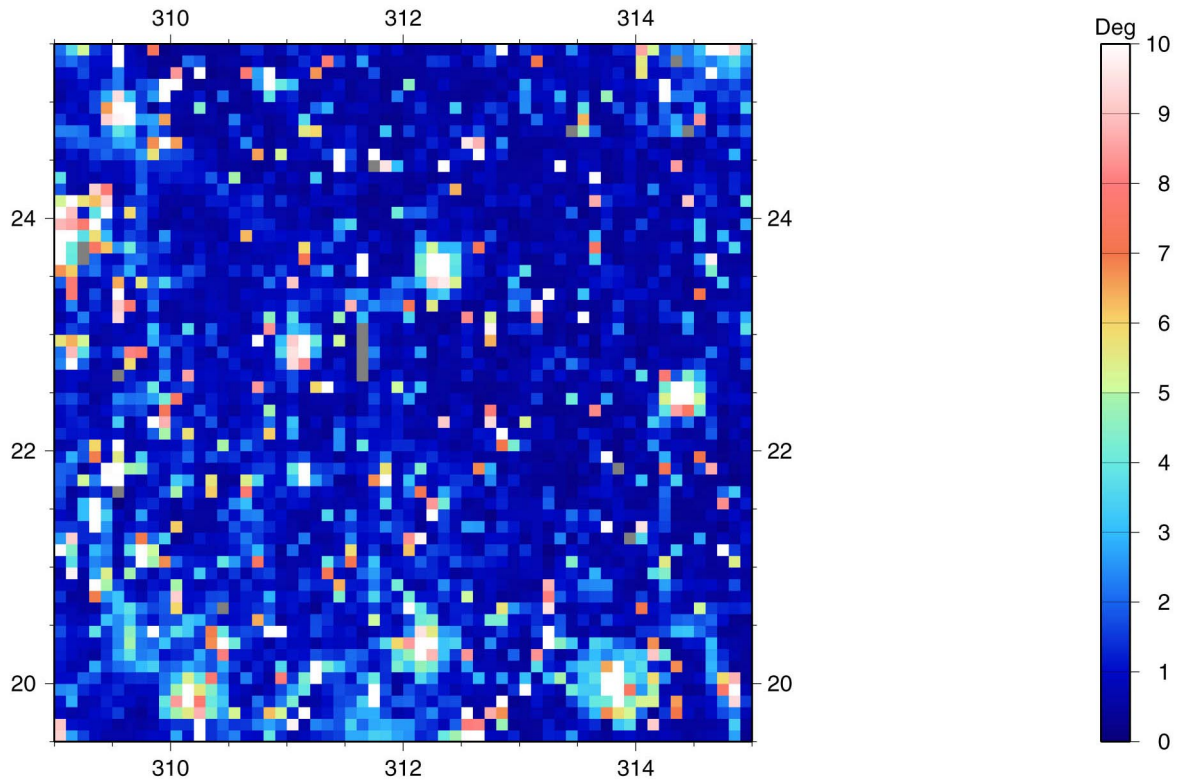


Site Hectometer Slope Map: VL1



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vi1_y100.slope



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