



MSL Project Status and Landing Site Selection Schedule

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MSL Mission Manager

On behalf of MSL project, especially
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EDL Team: A. Steltzner et al.
Flight System: M. Wallace/H. Eisen et al.

Project Status



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- Significant progress on major spacecraft components
 - MSL is really 3 spacecraft
 - Cruise stage
 - Descent stage
 - Rover
- Significant progress on instruments
 - MARDI delivered (DAN in transit)
 - All others coming soon (by Dec 08/Jan 09)
- Major flight and ground software deliveries
 - Support critical system testing and preparing for cruise activities
- Lots of work to go, especially in system integration, the system level test program, and software development



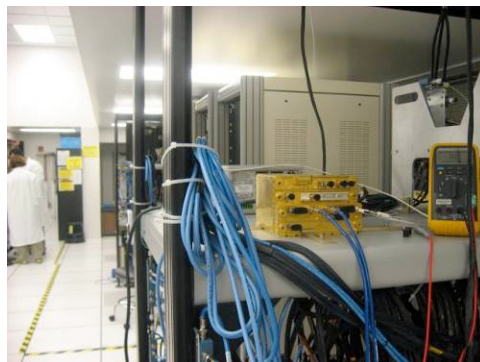
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System Integration and Test

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AEGSE: Single Slice Rack



STB: FS SDST



ATLO: SCARF w/ Cradle & Motor Installed



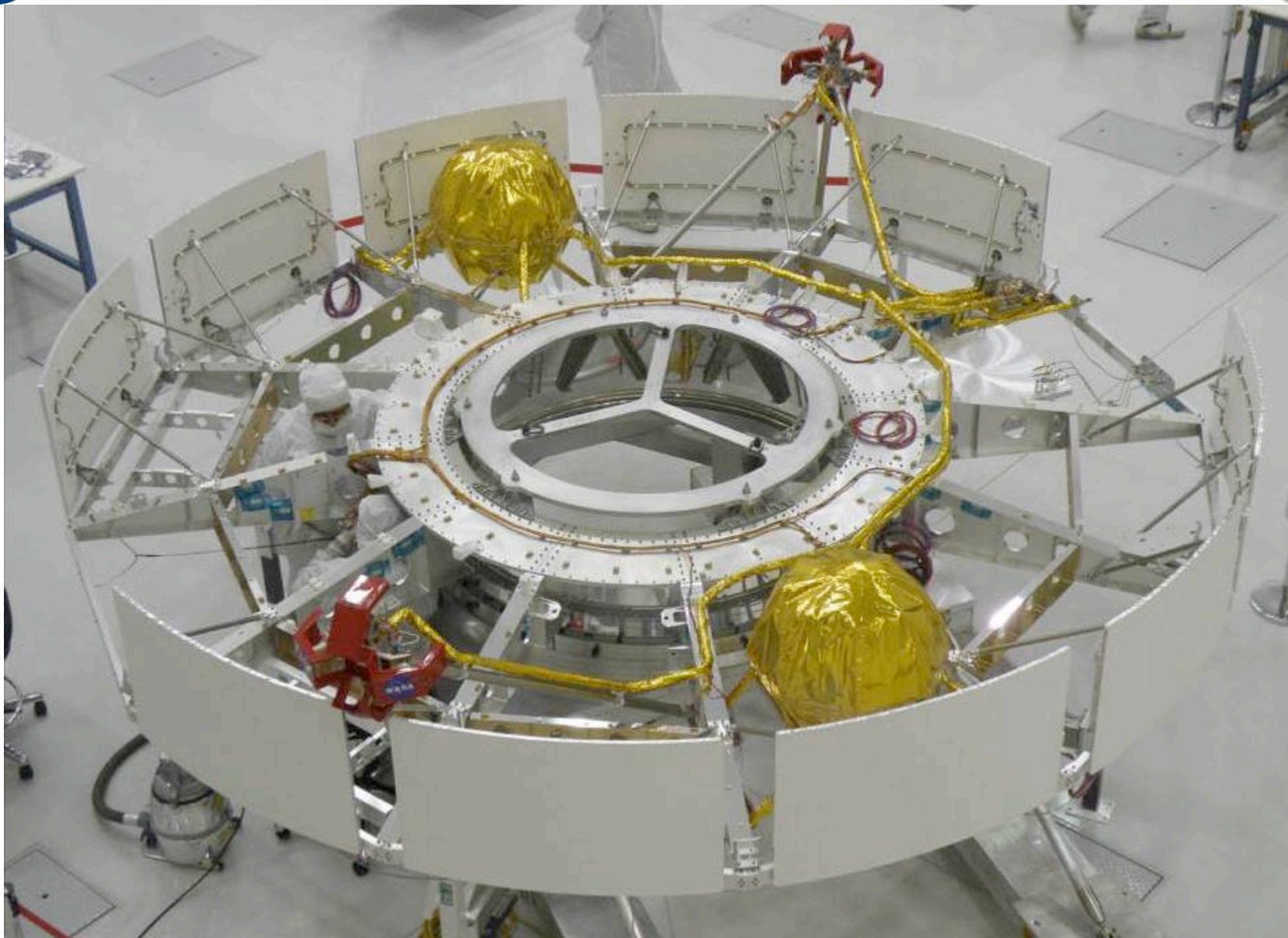
ATLO: FM RPAM-A (covered) & RPAM-B

Cruise Stage



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Descent Stage Prop Integration In-progress

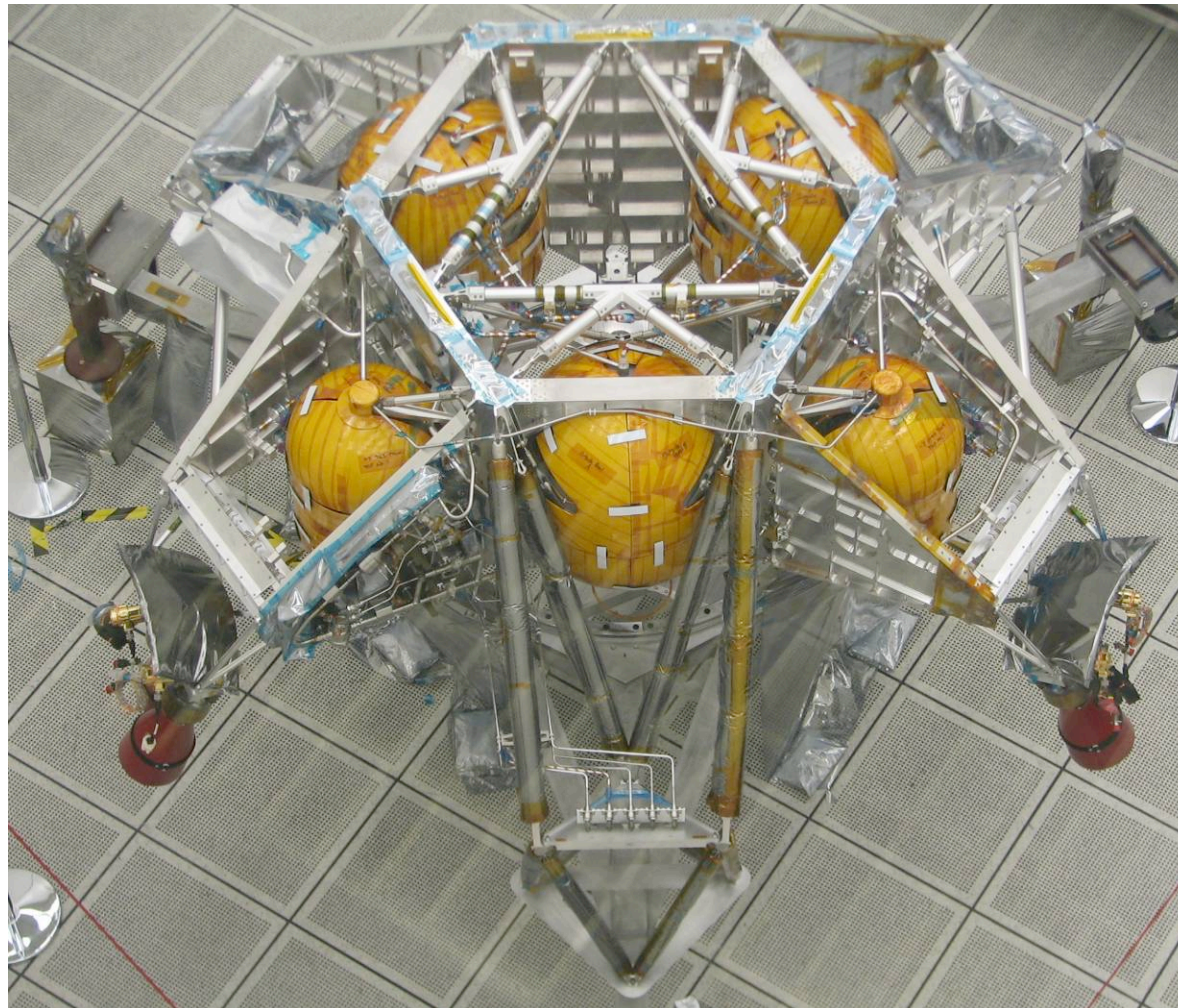


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**Propellant
Tanks (x3)**



**Pressurant
Tank (x2)**

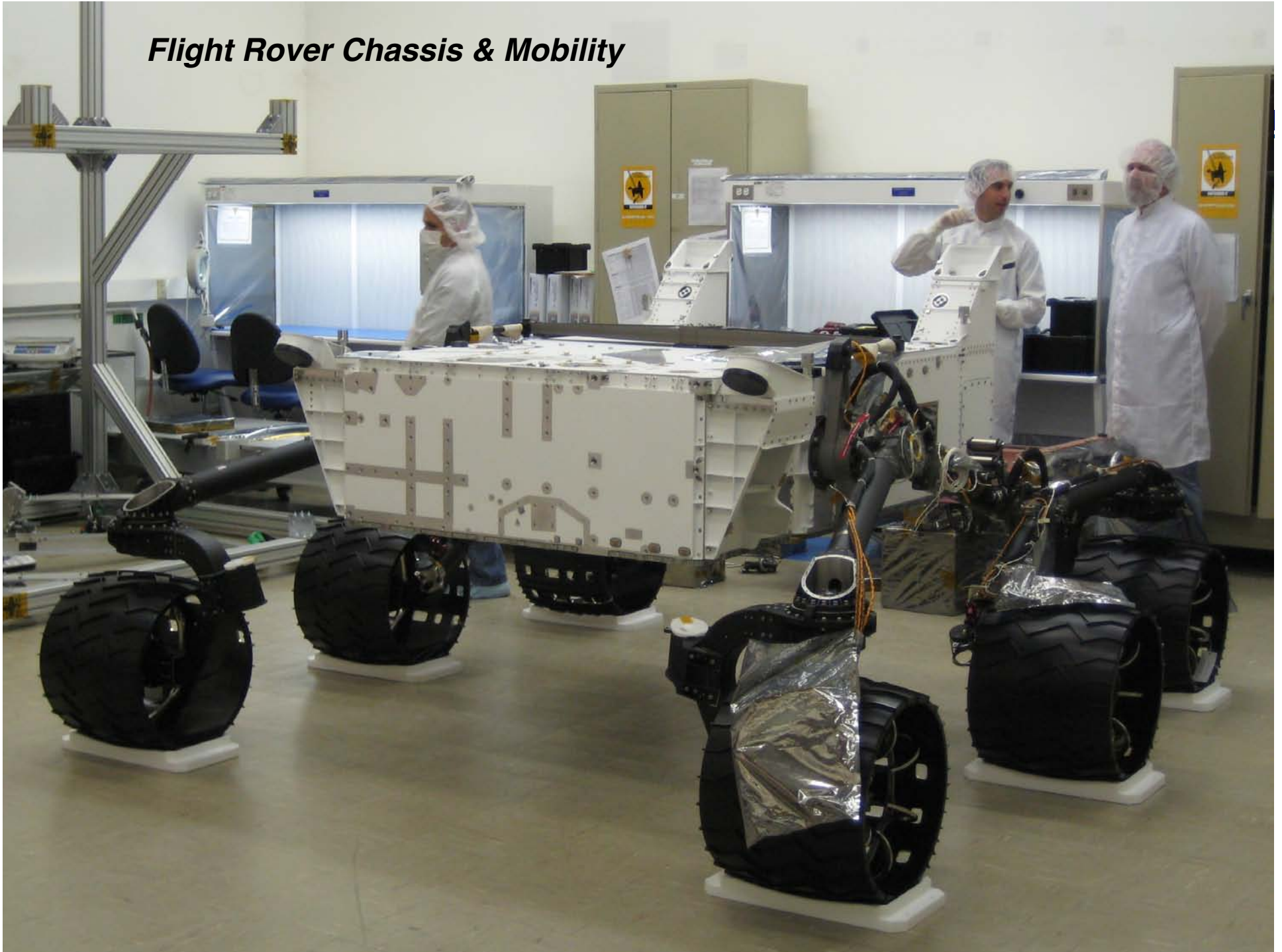
PCA

MLE

**Service
Valves**

TDS (radar) Truss

Flight Rover Chassis & Mobility

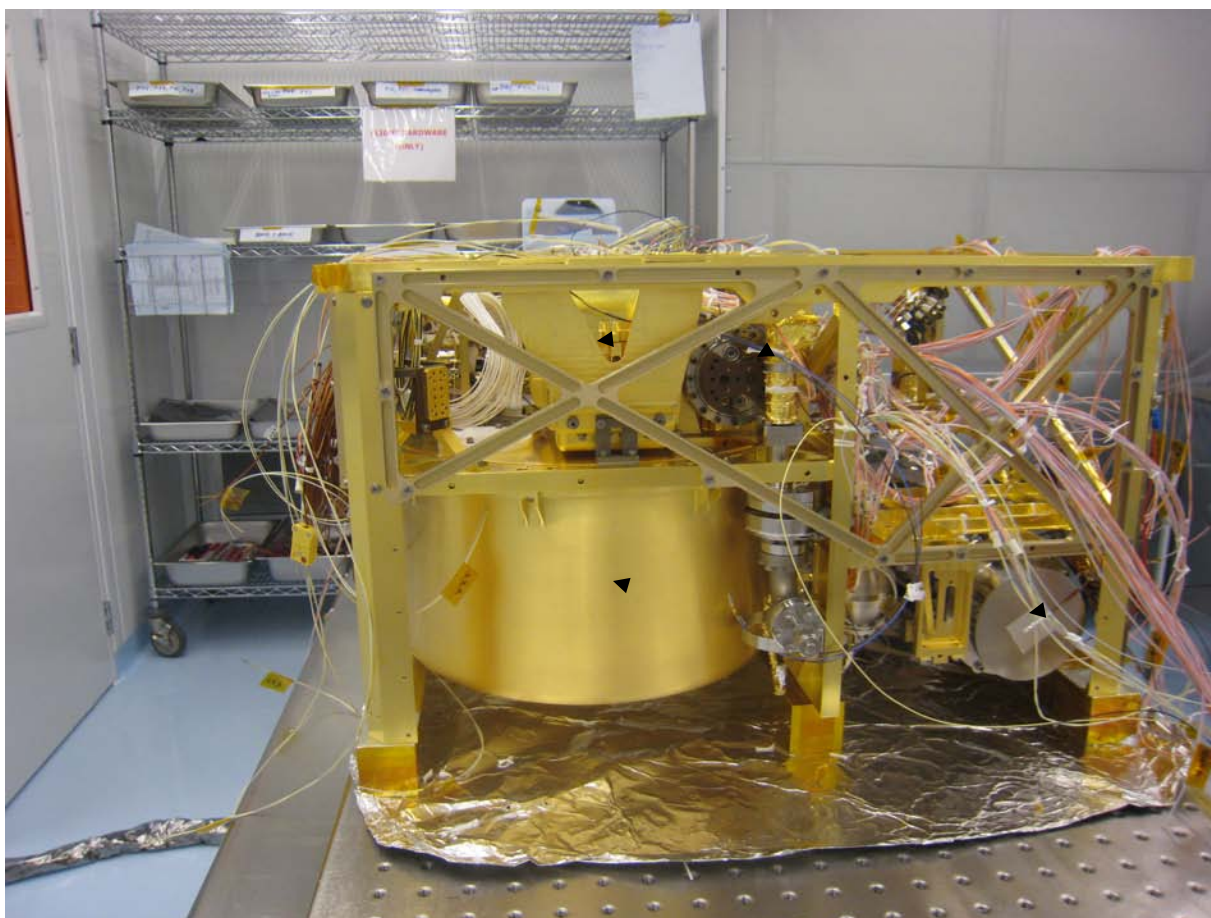




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SAM Suite in Clean Room

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QMS

RF Electronics

TLS

SMS cover



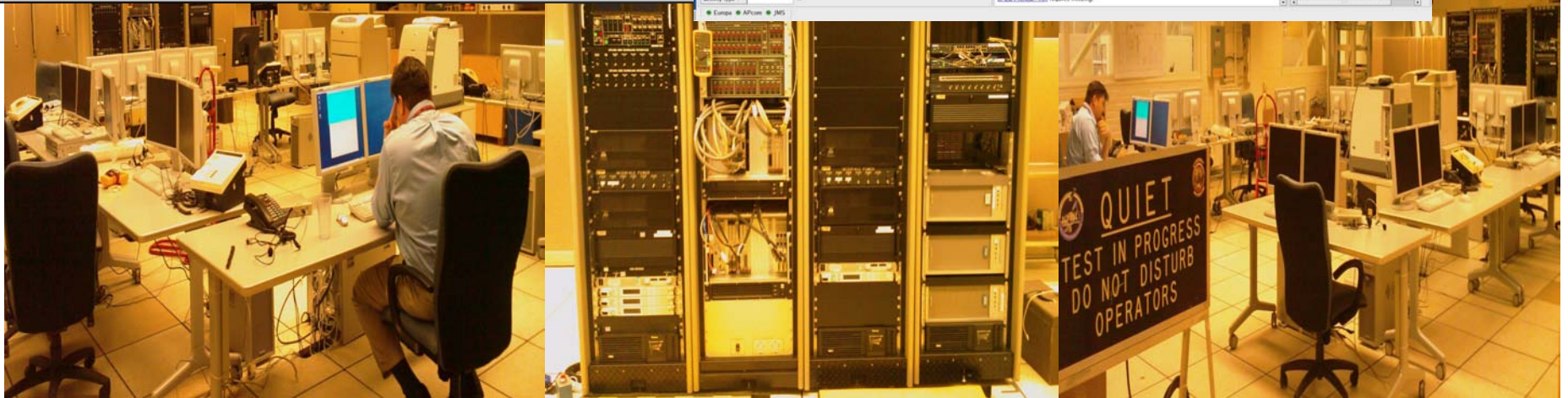
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Ground System

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The screenshot displays the Maestro ground system interface. The main window shows a 3D terrain map of Mars with various targets marked. A list of targets is visible on the left, including 'Front Hazcam' and 'Sol 944'. A detailed activity schedule is shown on the right, listing tasks such as 'RAC doc TEGA cover 4', 'RAC doc OM vid', and 'RAC doc TEGA cover 5'. The interface includes a search bar, a list of targets, and a detailed activity schedule.



**Important Change (for the better)
since 2nd Workshop
(and Dec. 4th Morning After)**



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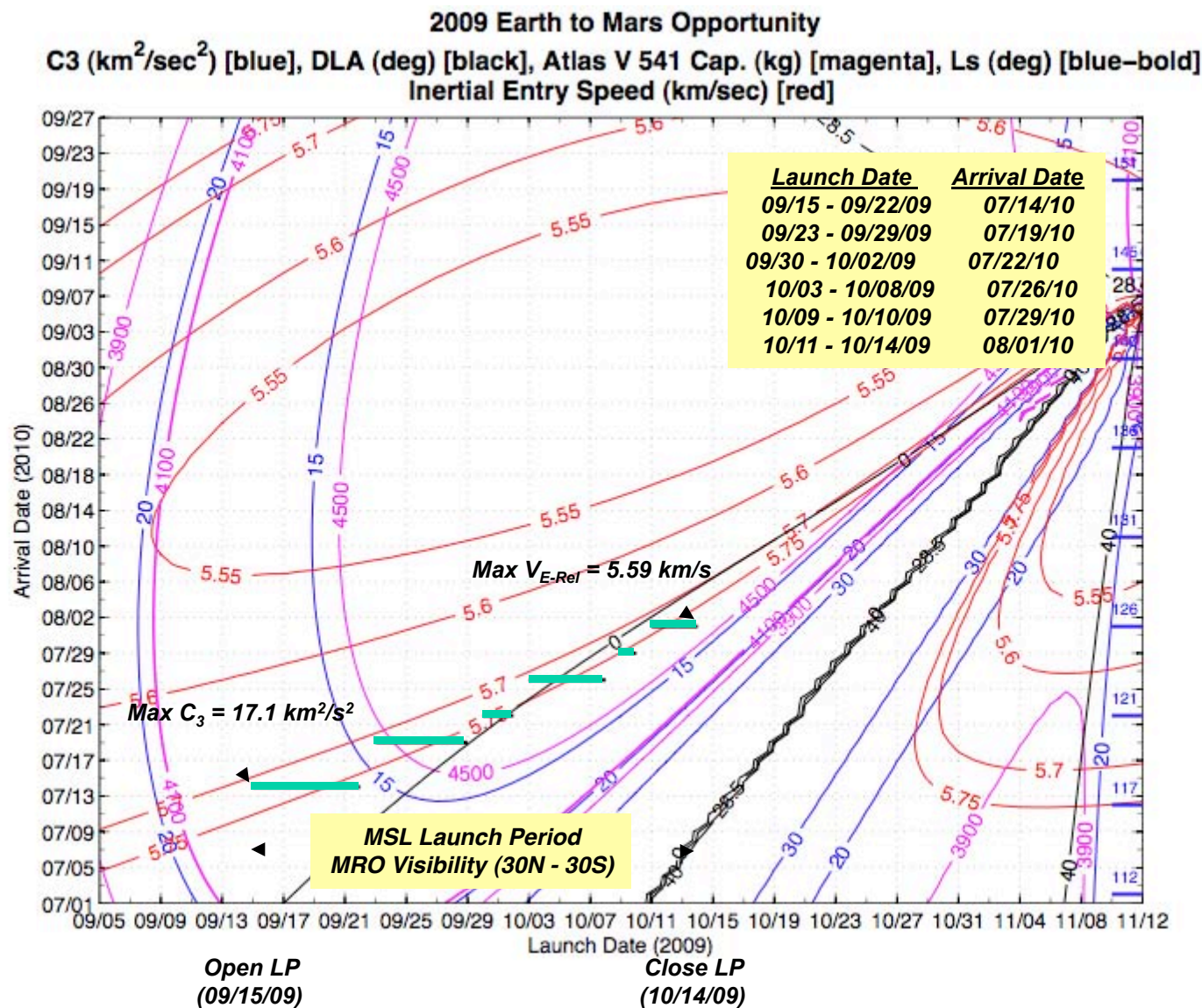
- Based on improved UHF link analysis from trajectory and telecom, we were able to merge the multiple target specs (each covering specific latitude bands) into a ***single target spec covering 30N-30S***
 - ***All current candidate sites reachable with in-flight retarget beginning at TCM-1 from central launch vehicle target***
 - Considerably simplifies targeting and backup site strategy
 - No hemispheric or band-specific backups needed
 - There is a single launch period but still multiple arrival dates



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Status – Launch/Arrival Strategy

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Project Technical Status Related to Landing Site Selection



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- Acquiring orbiter and atmospheric model data sets
 - Examples: Mono and stereoHiRISE and CTX images, MCS, CRISM, GCMs, site dependent mesoscale atmospheric models
 - Tremendous support from MRO project and science team, and CDP team
- Processing data sets into usable products (more from Golombek+posters)
 - Digital terrain models at the 1m scale, rock counts, formatted atmospheric density maps, winds, etc
- Use of these products in detailed site by site engineering performance and safety analyses
 - Processing information currently available on site environments against system performance parameters
- Motor actuator heaters have been incorporated to best extent possible in rover design



Current Status on Site Evaluation



EDL Safety:

- Preliminary analysis complete
 - Atmospheric conditions including winds
 - Terrain affecting radar/powered descent (100-1000 m scales) over full ellipses
 - Rover-scale touchdown slopes (2-5 m scales) for a subset of the terrain (data availability)
 - Rock density for a subset of the terrain (data availability)
- All current site candidates acceptable at “>95% success level”
 - *Site to site variability in success level is small and is outweighed by remaining uncertainties*

Surface Performance:

- Preliminary work suggests
 - Motor actuator low temperature torque performance, and energy use for heaters finds all current sites meet at least Level-1 science rqmts
 - We don’t know the second digit of rover science efficiency yet pending additional results based on flight model actuators, and site by site mobility assessment

All sites are currently acceptable to project

- Engineering not a discriminator at this workshop



Upcoming Engineering Analysis



- Additional site coverage
 - More high resolution DTM's and rock hazard maps covering full ellipses and selected go-to areas
- Tuning of system “knobs” to improve performance
 - More data on rover touchdown capability from test program, more highly specific EDL simulations
 - Preliminary assessments available by late 10/08
 - Continuing in excruciating detail for site finalists
- Additional test data on actuator torque margin at low temperature, impacts on lifetime, effect of gradient heating
 - Flight actuators available for test next month, thermal gradient tests by end of CY08
- Additional analyses of “Go-To” traverses
 - Rover planners brought on board, first order analysis of each site by late 10/08
 - Detailed analyses on finalists

Landing Site Selection Remaining Major Events

(excludes internal/subsystem reviews and ongoing meetings)



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- **Third Community Workshop 9/15-17/08**
 - Heavily science focused
- **“Morning After II” Late Oct/Early Nov 08**
 - Project + PSG +Reps from external science community
 - Combine current engineering assessments on site by site basis with science rankings
 - => 3 finalists for highly detailed final study
- **Brief HQ on status ~11/08**
- **Engineering Assessment Status Workshop 1/09**
 - Status detailed engineering assessment, special attention on actuators/traverse
- **Fourth Community Workshop Early 4/09**
 - Final science assessment of site candidates
- **EDL Landing Site Safety Review Early 4/09**
 - Detailed site by site EDL engineering risk assessment
- **Project Final Landing Site Selection Meeting 4/09**
 - “Final” convolution of detailed engineering (EDL and traverse) and science assessment
 - => Recommended site ranking from Project
- **Independent Certification Review ~5/09**
- **Brief HQ ~6/09**
 - final site approval